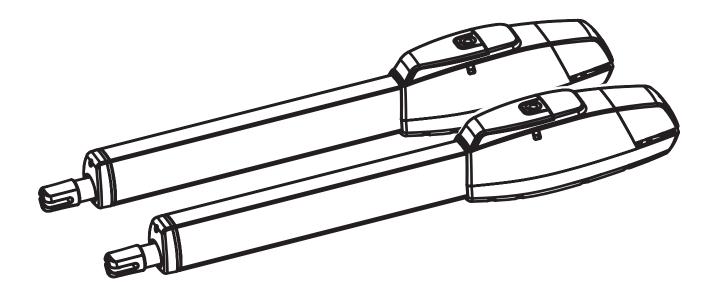


## **TORO 24**



## **SWING GATE OPENER**

**INSTALLATION MANUAL** 



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# IMPORTANT SAFETY PRECAUTIONS <u>WARNING</u>

## To reduce the risk of injury:

READ THE FOLLOWING DIRECTIONS. DO NOT START UNTIL YOU HAVE READ AND UNDERSTAND THESE DIRECTIONS. IF THERE IS SOMETHING YOU DON'T UNDERSTAND CALLUS.

Never let children operate or play with gate controls. Keep the remote control away from children.

Always keep people and objects away from the gate. No one should cross the path of the moving gate.

This operator must be tested monthly. The gate must reverse on contact with a ridged object or stop when an object activates the non-contact sensors. After adjusting the force or the limit travel, retest the gate operator. Failure to adjust and retest the gate operator properly can increase the risk of injury.

Use the emergency release only when the gate is not moving.

Keep gates properly maintained. Have a qualified service person make repairs to gate hardware. It takes many years of experience to make proper adjustments to gate hardware or operators.

This entrance is for vehicles only. Pedestrian must use separate entrance.

There is nothing on a gate operator that is easily repaired without a great deal of experience. Save yourself some time and call a qualified Gate Service Contractor who knows your type of gate operator.

#### SAVE THESE INSTRUCTIONS FOR FUTURE REFERENCE

## INSTALL THE GATE OPERATOR ONLY WHEN YOU HAVE READ THE FOLLOWING:

- \* Confirm that the gate operator being installed is appropriate for the application.
- \* Confirm that the gate is designed and built according to current published industry standards.
- \* Confirm that all appropriate safety features and safety accessory devices are being incorporated, including both primary and secondary entrapment protection devices.
- \* Make sure that the gate works freely before installing the operator.
- \* Repair or service worn or damaged gate hardware before installation of the gate operator.
- \* Eliminate all gaps in a swinging gate below a 4 foot height that permits a 4 inch sphere to pass through any location, including the hinge area of the gate.
- \* Operator must be disconnected from the power source before attempting any installation of accessories.
- \* Install this gate operator according to our installation instructions.
- \* Adjust the operator load sensing device to the minimum force setting that will still allow for reliable gate operation.
- \* Install the operator inside the fence line (do not install the operator on the public side of the fence line).
- \* Install a proper electrical ground to a gate operator.
- \* Controls intended for user activation must be located at least six feet (6') away from any moving part of the gate and where the user is prevented from reaching over, under, around or through the gate to operate the controls. Outdoor or easily accessible controls shall have a security feature to prevent unauthorized use.
- \* The stop and/or reset buttons must be located in the line of sight of the gate. Activation of the reset control shall not cause the operator to start.
- \* Install a minimum of two(2) WARNING SIGNS, one on each side of the gate where easily visible and take pictures of installation.
- \* Test all safety features for proper function before placing the automatic vehicular gate into service.
- \* Train owner/users about basic functions and safety features of the gates system, including how to turn off the power and how to operate the manual disconnect feature.
- \* leave safety instructions, product literature and installation manual with end user.
- \* Explain to the owner/user the importance of routine service and retesting on a monthly basis.

## **DIFFERENT UL 325 CLASS TYPES**

#### Class one: Residential

A vehicular gate operator intended for use at a home of one to four single family dwellings, garage or parking area.

#### Class two: Commercial or General Public Access

A Vehicular gate operator intended for use at a commercial location or building such as a multi-family housing unit (five or more single family units), hotel, garages, retail stores, other buildings servicing the general public.

#### Class three: Industrial or limited access

A vehicular gate operator intended for use at an industrial location or building such us a factory, loading dock area, or other locations not intended to service the general public.

#### **Class four: Restricted Access**

A vehicular gate operator intended for use at a guarded industrial location or building such as airport security areas or other restricted access locations not servicing the general public where unauthorized access is prevented via supervision by security personnel.

#### Other components required to satisfy UL 325

Each class must have a primary and secondary means to sense and react to obstructions within two seconds.

#### The six types of obstruction sensing systems are:

#### Type A:

Inherent obstruction sensing system. This system must sense and initiate the reverse of the gate within two seconds of contact with a solid object.

#### Type B1:

Provision for connection of a non-contact device can be used, such as a secondary protection.

#### Type B2:

Provision for connection of a contact sensor. Examples include an edge device or equivalent. This can be used for secondary protection.

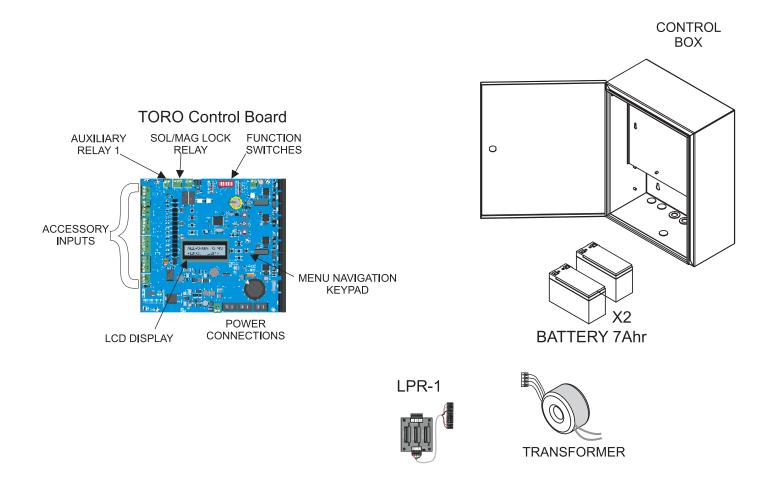
#### Type C:

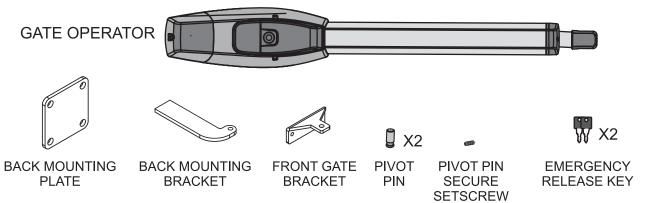
Inherent adjustment clutch or pressure relief valve.

#### Type D:

Provision for connection of or provided with and actuation device requiring continuous pressure.

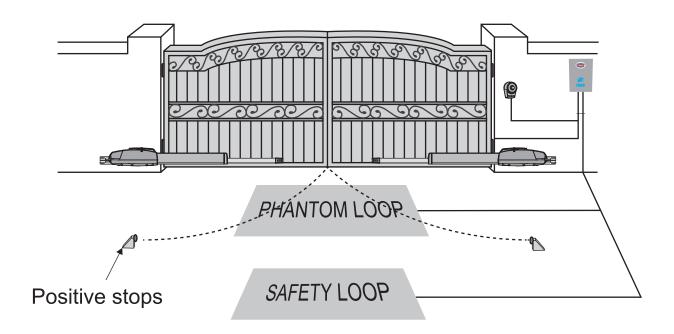
## PARTS IDENTIFICATION





NOTE: **Back mounting bracket** must be cut to fit geometry requirements. Use **back mounting plate** when a steel post is not available to weld the **back mounting bracket**.

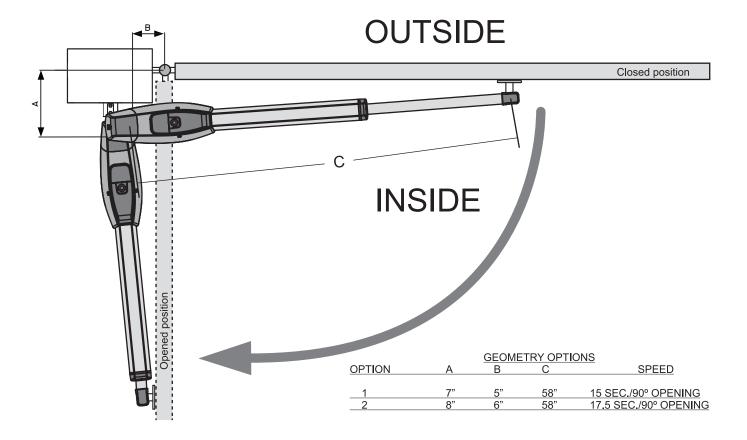
## **OPEN INSIDE INSTALLATION**



Comply with the measurements shown for proper installation. Adjust the gate structure to optimize for best automation performance, if necessary.

Before proceeding with installation, be sure that gate moves freely and that:

- 1) Hinges are properly positioned and lubricated.
- 2) No obstructions are in the path of the swinging gate.
- 3) No frictions between two leafs or with the ground while moving.

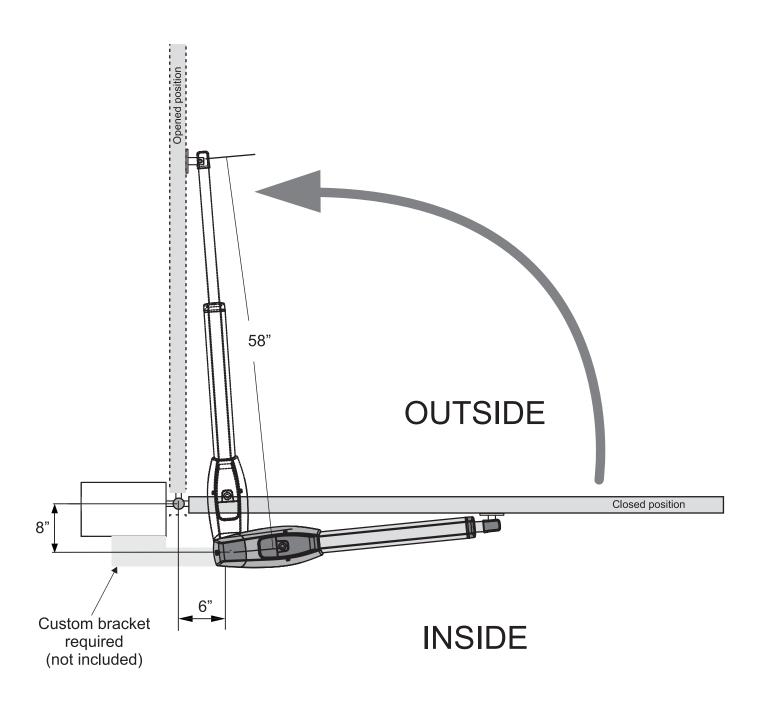


## **OPEN OUTSIDE INSTALLATION**

Comply with the measurements shown for proper installation. Adjust the gate structure to optimize for best automation performance, if necessary.

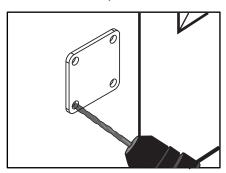
Before proceeding with installation, be sure that gate moves freely and that:

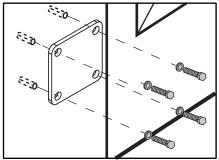
- 1) Hinges are properly positioned and lubricated.
- 2) No obstructions are in the path of the swinging gate.
- 3) No frictions between two leafs or with the ground while moving.

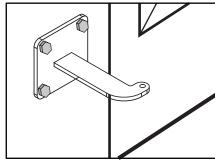


## **GATE OPERATOR INSTALLATIONS**

When a steel post is not available use the back mounting plate to have a welding surface.





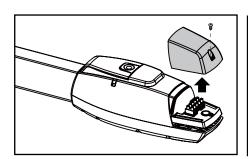


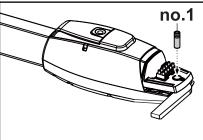
Mount the **back mounting plate** to the pillar using anchor bolts. Cut the **back mounting bracket** to fit the geometry and weld to the **back mounting plate** or the steel post (if available). NOTE: For OPEN OUTSIDE installation a custom mounting plate(not provided) is required to fit geometry.

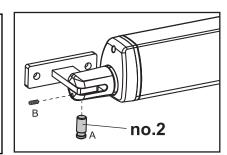
Remove the wire connection cover and attach the back mounting bracket with the pin. Release the gate operator and place the pin into the fitting position no. 1 and no. 2 shown below. Use the setscrew to hold pin no. 2 in position.

Make sure the gate operators are mounted in horizontal position especially in the CLOSE, OPEN and 45° positions.

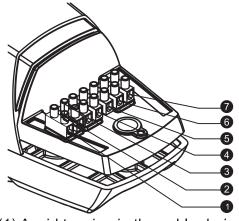
Prior to welding the front gate bracket on the gate leaf(if necessary), cover the gate operator to prevent damage from welding sparks.







#### **WIRE CONNECTION:**



0	White	Motor (+)
2	Yellow	Motor (-)
3	Red	+5V
4	White	INDEX
6	Black	COMMON
6	Blue	Limit Switch (Limit 1)
0	Green	Limit Switch (Limit 2)

- (1) Avoid tension in the cable during open and close cycles.
- (2) Always connect the grounding wire(GND)

## **EMERGENCY RELEASE**

In case of power failure, push the cover of release compartment and slide forward. Insert the key and turn clockwise to unlock, then turn the knob clockwise to release. To latch back to normal operation, simply reverse the procedures above.

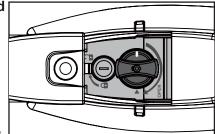
Step1. Push the cover of release compartment and slide forward

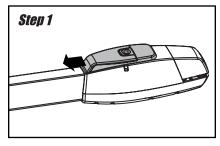
Step2. Insert the key and turn clockwise to the unlock position

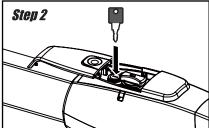
Step3. Turn the knob clockwise to release the motor.

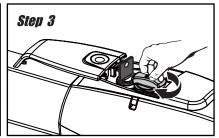
Make sure the White bar on the knob is on the position opposite to the triangle indication.

To restore the automation, simply reverse the above procedure.





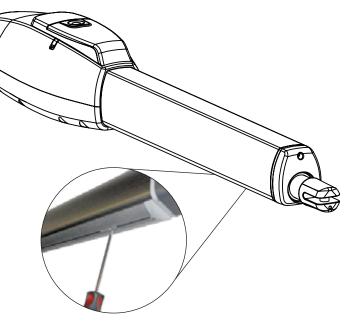




### LIMIT SWITCH ADJUSTMENT

#### EASY STEPS TO ADJUST LIMIT SWITCHES

- 1. Find the open and close limits on the bottom of the actuator.
- 2. Loosen the limit switch screws to allow it to slide and make the open and close adjustment.
- 3. Once the open and close limits have been set, tighten the screws to lock limits in place.



#### **SETTINGS MENU**

#### **ADVANCED FEATURES**



#### **ENTERING THE SETTINGS MENU**

Press the ENTER button twice to wake up the LCD display. Press the < (left) button to select ENGLISH.

Select SETTINGS, then press ENTER (the left <- arrow indicates selection).

Use the UP/DOWN buttons to scroll through the menu list. Make selection, then press ENTER. The < left button could be use to go back to previous screen.

#### **Setting TIME and DATE:**

From the **SETTINGS** menu select the **TIME & DATE**, then press **ENTER.** 

- Move cursor to TIME, then press ENTER to edit time. The time editor will then open. Use the < RIGHT/LEFT > buttons to move from hours to minutes and AM/PM and UP/DOWN buttons to change the time. Press ENTER button to save TIME.
- Move cursor down to DATE, then press ENTER to edit date. Use the < RIGHT/LEFT > buttons to position cursor and UP/DOWN buttons to change the date. Press ENTER to save the DATE.
- Once DATE is saved the weekday needs to be set. Use UP/DOWN buttons to scroll through the days of the week. Press ENTER when the correct day of the week is displayed.

#### **Setting Motor SPEED**

From the **SETTINGS** menu select **SPEED**, then press **ENTER**. In this sub-menu there are three settings that can be adjusted. Using **UP/DOWN** buttons move the cursor to selection and press **ENTER** to edit each of them.

- MAX SPEED: This can be adjusted from 50-100%. This is the maximum operational speed of the gate. Use the UP/DOWN buttons to change the % value and press ENTER to save.
- ACCELERATION: This can be adjusted from SLW (slow), MED (medium) and FST (fast). This is how fast the gate will ramp up (accelerate) at motor start. Use the UP/DOWN buttons to change the setting and press ENTER to save.
- SLOW/DOWN: This can be adjusted from 70-95%. This is the
  percentage of travel where the gate will start slowing down as
  the gate approaches the open or close limits. Use UP/DOWN
  buttons to change the % value and press ENTER to save.

#### **Setting Motor POWER**

From the SETTINGS menu select **POWER**, then press **ENTER**. In this sub-menu there are two settings that can be adjusted. Using UP/DOWN buttons move cursor to selection, then press **ENTER** to edit each of them.

- TORQUE: This can be adjusted for LOW, MED and HIGH. Use UP/DOWN buttons to change the setting and press ENTER to save.
- CURR. SENSE: This sets the way current sense is read. THLD (threshold) for normal operation(default). PRGV (progressive) for windy areas. Use UP/DOWN buttons to change from THLD and PRGV, then press ENTER to save.

#### Setting the 7 DAY TIMER:

From the SETTINGS menu select the **7/DAY TIMER**, then press **ENTER**.

- In the event list, select the **EVENT** # that you would like to program, then press **ENTER** button.
- Select the ACT. (action) by scrolling through the different actions

- then press ENTER when desire action is displayed.
- Set the time for the action. Using the UP/DOWN buttons to change the time and RIGHT/LEFT buttons to move from hours, minutes and AM/PM. Press ENTER button to save the action time
- Last, set the days of the week that you would like the action to be in effect. Use the UP/DOWN buttons to scroll through the days and the RIGHT button to toggle the day ON/OFF.

Repeat process for each event (1-10 events available). Action list:

- OFF (DISABLED) Nothing happens.
- **OPEN** (opens the gate once)
- OPEN & HOLD (opens the gate and holds it open. Only a close event or a close override command will close the gate.)
- CLOSE (closes the gate once)
- CLOSE & HOLD (closes the gate and holds it closed. Only an open event or an open override command will open the gate.)
- AUX RELAY ON (turns the auxiliary relay ON)
- AUX RELAY OFF (turns the auxiliary relay OFF)

#### **Setting LEAF DELAY:**

From the SETTINGS menu select the **LEAF DELAY**, then press **ENTER**.

- To select which leaf needs the delay press ENTER while the cursor blinks on the left side of DELAY LEAF. Cursor will then move to make selection, use UP button to toggle between ONE/TWO leaves, then press ENTER to save.
- Then, select DELAY and press ENTER to edit the delay. Cursor will then move to edit delay, use UP/DOWN buttons to set the delay (0.0 to 6.0 Sec). NOTE: This is only used on double gate.

**NOTE:** Leaf delay is for the open cycle of selected leaf. The close delay will be for the opposite of selected leaf.

#### **Setting AUXILIARY RELAY:**

From the SETTINGS menu select the **AUXILIARY RELAY**, then press **ENTER**. The Cursor is used to show selection.

- Using UP/DOWN buttons, select the function, then press ENTER.
- If PRE-WARN SIGNAL was not selected skip next step.
- If PRE-WARN SIGNAL was selected, the delay must be set.
  Use the UP/DOWN buttons to set the pre-warn delay, then press
  ENTER to save.

Functions that can be program to the Auxiliary relay:

PRE-WARN SIGNAL: This is used to turn on a strobe light or a siren with a delay before the gate starts to move)

MOVING SIGNAL: This will activate the relay and keep it active as

the gate is in motion. **ALARM ALERT:** This will activate the relay when the gate has been

tempered with. Use as an alarm sensor output.

OPENED SIGNAL: This will keep the relay active while the gate is in the fully opened position.

CLOSED SIGNAL: This will keep the relay active while the gate is in the fully closed position.

NOTE: an asterisk will appear on selected function.

#### **Setting SERVICE CYCLE:**

From the SETTINGS menu select the **SERVICE CYCLE**, then press **ENTER**.

An on board cycle counter is integrated and can be used to program a service call. It can be set at a predetermine # of cycles.

- To set the number of cycles press **ENTER** button. The cursor will then move to the 0 on the ones position.
- Use the RIGHT/LEFT buttons to move cursor to other positions and the UP/DOWN buttons to increase/decrease values. Press ENTER button to save.

**NOTE:** If the service cycle is programmed, the board will start to count down every cycle and alert when the remaining cycles reach 0. The alert is the audible alarm that will beep every hour for 1 minute. If no service cycle was programmed, nothing happens.

#### **SETTINGS MENU**

#### **Setting LIMIT SW CONFIGURATION:**

From the SETTINGS menu select the **LIMIT SW CONF.**, then press **ENTER**.

- INDEX: It's used for speed control using its feedback. It's also used to keep track of gate position.
- BEMF: This is used for applications where the amount of conductors are limited and is difficult to run new wiring. Using this option only the limit switches will be used and the motor will not have speed control.
- To toggle INDEX and BEMF press the ENTER button to edit.
   Use the UP/DOWN buttons to toggle and press ENTER to save the setting.

#### **Setting to DEFAULT:**

From the SETTINGS menu select the **SET TO DEFAULT**, then press **ENTER**.

In this section the user is allowed to set the programming back to factory settings (factory default).

Use the **UP/DOWN** buttons to select the parameter that you would like to set back to factory default and press **ENTER**. **DEFAULT ALL** will set every parameter back to factory settings. This very useful when you are not sure what has been programmed.

#### **DIAGNOSTICS MENU**



#### **ENTERING THE DIAGNOSTICS MENU**

If LCD display is not awake, press the ENTER button twice to wake up the display.

Press the < left button to select ENGLISH.

Using the UP/DOWN buttons select DIAGNOSTICS, then press ENTER. The < left button could be used to go back to previous screen.

Using the  $\mbox{UP/DOWN}$  buttons move to selection, then press  $\mbox{ENTER}.$ 

- GATE STATUS: This displays the status of the gate (OPENING, CLOSING, OPENED, CLOSED, STOPPED or STOPPED ERD)
- METER: The meter will display Battery Voltage, LINE IN Voltage, Motor 1 current draw and Motor 2 current draw. Use the UP/DOWN buttons to scroll thru the different items.
- MOTOR ONE: This will display the motor one speed and position of the gate travel. Use the UP/DOWN to scroll to SPEED and TRAVEL.
- MOTOR TWO: This will display the motor two speed and position of the gate travel. Use the UP/DOWN to scroll to SPEED and TRAVEL.
- EVENT LOG: This is a very useful event log that displays up to 25 abnormal events with date and time stamp that are recorded as they happen. Use the UP/DOWN buttons to scroll thru the events.
- CYCLE COUNT: This will display the following cycle counts:

LIFE CYCLES MONTH CYCLES DAY CYCLES

**SERVICE COUNT:** This will show the **REMAINING CYCLES.** This will only show if a service was programmed. An indication to reset will show when remaining cycles reach 0

#### **MENU DESCRIPTION**

**<ENG:** English selection by pressing < left button.

**ESP.>**: Spanish selection by pressing > right button.

1. SETTINGS: Settings menu selection by pressing enter while settings is selected.

1.1 **TIME & DATE:** This menu is to edit/adjust time and date (including day of the week)

#### 1.2 **SPEED**:

1.2.1 **MAX SPEED:** This is the maximum speed for the motor

1.2.2 **ACCELERATION:** This is the acceleration rate (range: slow, medium and fast).

1.2.3 **SLOW/DOWN:** This the percentage of travel where the motor will start slowing down as it approaches the limits.

#### 1.3 **POWER**:

1.3.1 **TORQUE:** There are three levels of torque (Low, Med and high).

1.3.2 **CURR. SENSE**: Current sense is to select the way the board reads current from the load. Threshold (**THLD**) is default and is recommended for normal operation. Progressive (**PRGV**) is for gates installed where wind is a factor.

#### **1.4 7/DAY TIMER**

1.4.1 **EVENT 1**: There are 10 programmable events.

1.4.2 **EVENT ACT.**: This is where the actions is selected.

1.4.3 **TIME**: Time when the action takes place. 1.4.4 **DAYS (ACTIVE)**: Days that require the the action to be active. Each day needs to be

the action to be active. Each day needs to be turn on manually using the > right button to toggle ON/OFF.

#### 1.5 **LEAF DELAY**

1.5.1 DELAY LEAF: This is for the leaf selection.

1.5.2 DELAY: To set the delay of selected leaf.

#### 1.6 AUXILIARY RELAY

1.6.1 **RELAY ACTION:** Selection of the action for the relay function.

These are the available actions.

1.6.1.1 **OFF (INACTIVE)** 

1.6.1.2 PRE-WARN SIGNAL

1.6.1.2.1 **DELAY** 

1.6.1.3 MOVING SIGNAL

On when gate is in motion.

#### 1.6.1.4 ALARM SIĞNAL

On when tempered with operator.

1.6.1.5 OPENED SIGNAL

On when gate fully open.

1.6.1.6 CLOSED SĬGNAL

On when gate fully closed.

#### 1.7 SERVICE CYCLE

1.7.1 **SERVICE CYCLE COUNT:** This is used to program a service call. You set the number of cycles you want the gate to run before the customer gives you a call. The audible alarm will notify the end user with double beep when it's time for the service call.

#### 1.8 LIMIT SW CONF.

1.8.1 INDEX: This is the default configuration. it uses a hall effect sensor for speed control and to keep track of the gate position.

1.8.2 BEMF: This is an option to run only on limit switches. NOTE: Not fully functional yet

#### 1.9 SET TO DEFAULT

1.9.1 DEFAULT ALL: This selection will set

all parameters to factory settings. 1.9.2 DEFAULT SPEED

1.9.3 DEFAULT POWER

1.9.4 DEFAULT 7/D TMR

1.9.5 DEFAULT LEAF DLY

1.9.6 DEFAULT RLY FUNC

1.9.7 DEFAULT SVC C

1.9.8 DEFAULT SW CONF.

## 2. DIAGNOSTICS: Diagnostics menu selection by pressing enter while diagnostics is selected.

2.1 GATE STATUS
2.2 METER
2.3 MOTOR ONE

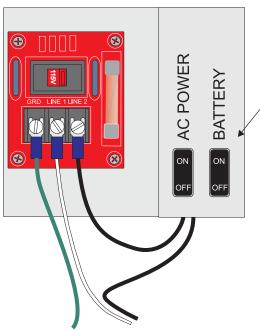
2.4 MOTOR TWO

2.5 EVENT LOG

2.6 CYCLE COUNT

## **ELECTRICAL CONNECTION**

#### OPERATORS **MUST** BE PROPERLY GROUNDED!



For power, a minimum of a 20-Amp dedicated circuit breaker is needed.

Power & Battery Switches



**NOTE:** When applying 230V to operator make sure voltage switch is flipped to 230V position.

Power connection	115VAC	220VAC Single Phase
LINE 1 =	115V HOT	220V LINE 1

**LINE 2** = 115V N 220V LINE 2

**GND** Connect to ground. Use a proper **ground rod** for a ground reference.

Use the shortest and thickest wire possible for ground.

## For power wire enclosure use UL listed conduits.

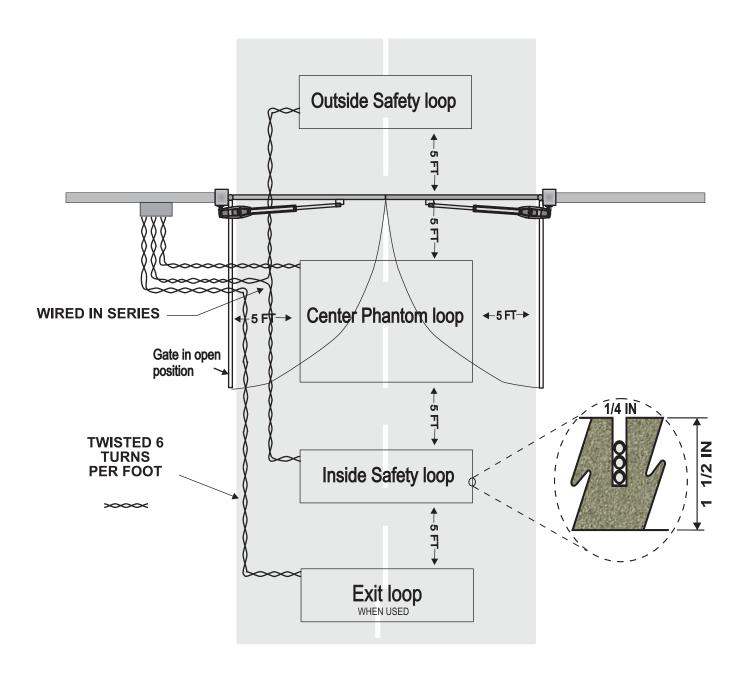
All gate operators MUST be properly grounded.

A proper ground in a gate operator installation minimizes or prevents damage from an electrical charge, such as a near lightning strike or an electrical static discharge.

Use a single wire for the ground. **DO NOT** splice two wires for the ground. If the wire breaks or is cut, replace it with a single length. **NEVER** use two wires for the ground.

Check with your City code for proper earth ground rod type and proper grounding procedures.

## **SWINGER LOOP LAYOUT**



This is a normal loop layout. Remember when connecting to an All-O-Matic circuit board you use the normally closed contacts (N.C.) from the safety loop detector and normally open contacts from the exit and phantom loop detectors. You must twist the loop wires from the exit point of the saw cut of each loop all the way to the loop rack, no exceptions.

The TORO 24 control box includes the plug-in loop rack for EXIT, PHANTOM and SAFETY (reverse) loop detectors.

## **GENERAL LOOP INSTALLATION GUIDELINES**

The following loop installation guidelines are for installing typical driveway loops for access control applications (i.e. parking gates, sliding gates, swing gates etc...) Always consult with loop detector manufacturers for specific equipment guidelines. This will confirm that the proper configuration and installation techniques are applied for your application.

Useful information about inductive loops:

- A. The typical sensing height is 2/3 of the shortest leg of loop (in feet) Therefore a 4' x 8' loop typically has a detection height of 2.6'.
- B. The inductance of a conventional four-slide loop can be estimated using the formula:

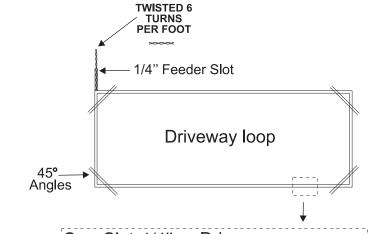
 $L = P \times (T^2 + T) / 4$  Where L = Loop Inductance in microHenries P = Loop Perimeter in feet T = Number of turns of wire in saw slot

Therefore a 4' x 8' loop with 3 turns would be:

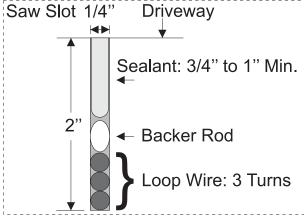
Suggested guidelines for loop installation:

Loop wires should be twisted 6 turns per foot, and twisted from saw slot to the detector. If possible start twisting the wires from the edge of the loop.

All 90 degree corners should be chamfered so that the course of the wire does not change direction sharply but rather at shallower angles of 45 degrees or less. Core drilling of the corners achieves the same effect but can still lead to failure due to sharp edges remaining in the corner area.



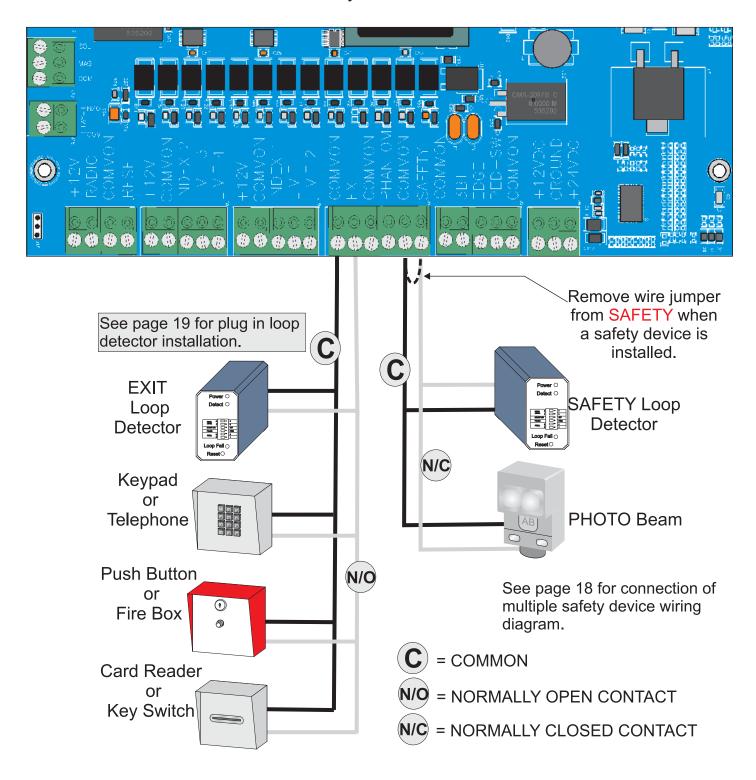
Loop Perimeter	# of Turns
6' - 12'	6
13' - 20'	5
21' - 60'	4
61' - 240''	3
241 & Up	2



## **ACCESSORY CONNECTIONS**

The circuit board 12 or 24VDC output provides up to 500 mAmps of power for accessories. More than two or three accessories will require a separate power supply.

NOTE: 12 or 24VDC Accessories only.



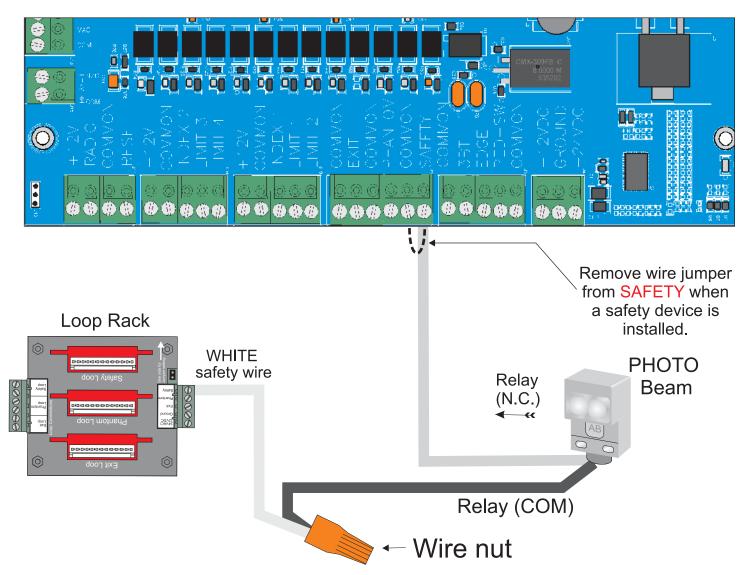
## **MULTIPLE SAFETY DEVICES CONNECTIONS**

Multiple SAFETY devices installed together must be connected in series. Locate the white loop rack safety wire and connect with common wire of second device. Dry contact (N.C.) from second device goes to "SAFETY" on the circuit board. Before installing the accessory devices, remove the wire jumper from the SAFETY position on the control board.

### Safety wire connections

From Loop rack	to	Second Accessory	
White safety wire	То	Relay COM	

From Second Accessory To		<b>Board pin</b>	
Relay N.C.	То	SAFETY	

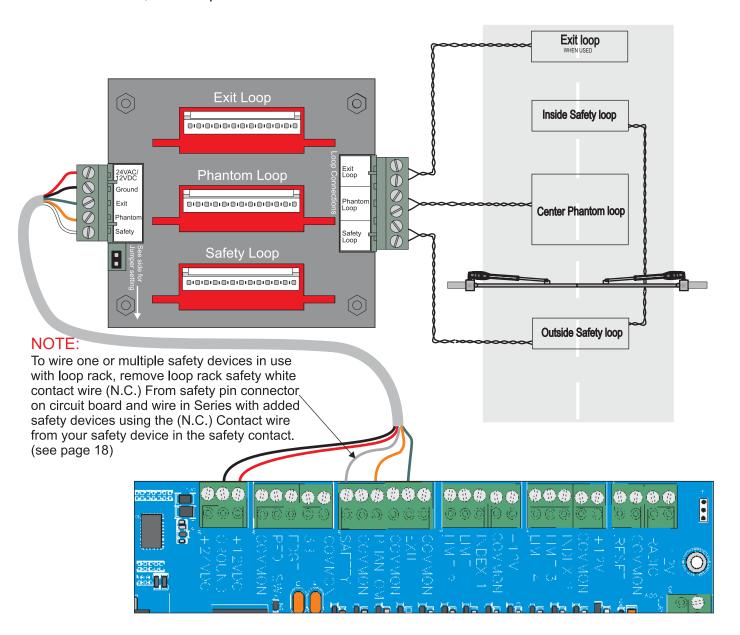


This diagram is for the relay wires of the safety devices, two wires to the board connections (one from each device) and two wires to the orange wire nut.

## LPR-1 LOOP RACK INSTALLATION

This is a typical loop configuration for a gated driveway. Remember when connecting to an All-O-Matic circuit board the safety (reverse) uses <u>normally closed contacts</u> from the loop detector, thewire jumper from the safety connector needs to be removed when a safety loop is inatalled.

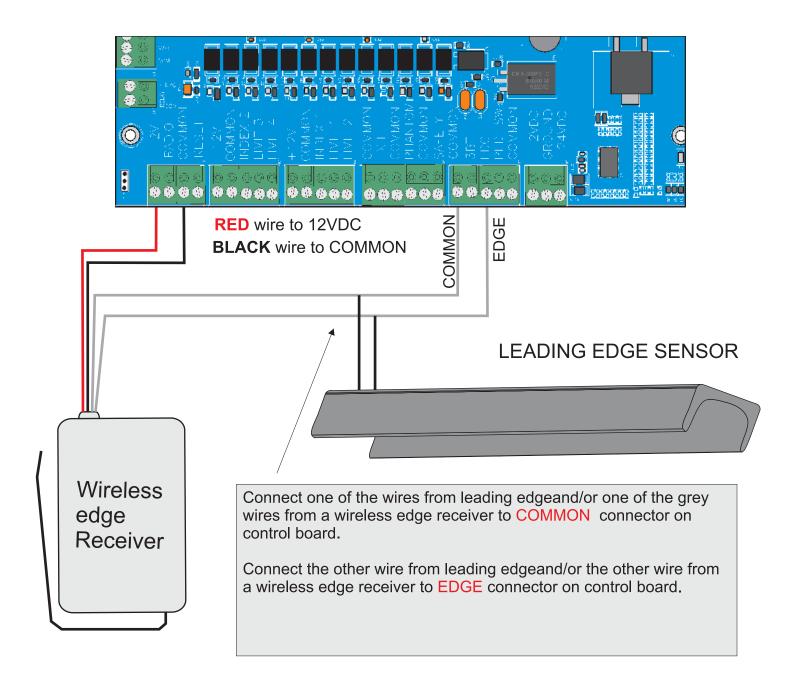
You must twist your wires from your exit point of the saw cut all the way to the loop detectors, no exceptions.



#### **Compatible Detectors**

Brand	Model No.	Jumper setting	
Reno A&E	H2		OFF
EDI	LMA-1800-LP		OFF
Diablo Controls	DSP-40S	• •	ON

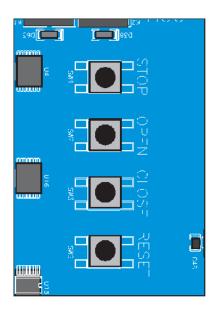
## LEADING EDGE CONNECTION



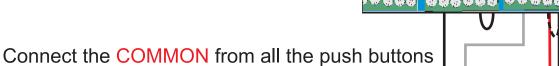
A wireless contact sensor such as one that transmits radio frequency (RF) signals to the gate operator for entrapment protection functions shall be located where the transmission of the signals are not obstructed or impeded by building structures, natural landscaping or similar obstruction. A wireless contact sensor shall function under the intended end-use conditions.

## THREE BUTTON STATION SYSTEM

See push button connections below.



A three button station was integrated on the board to make adjustments easier when setting limit switches and adjusting ERDs.

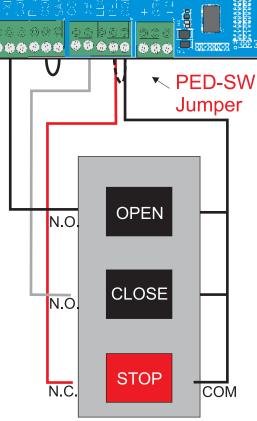


Connect OPEN push button N.O. contact to EXIT input on the board.

to **COMMON** input on the board.

Connect CLOSE push button N.O. contact to 3BT input on the board.

Connect STOP push button N.C. Contact to PED-SW input on the board and remove PED-SW jumper.

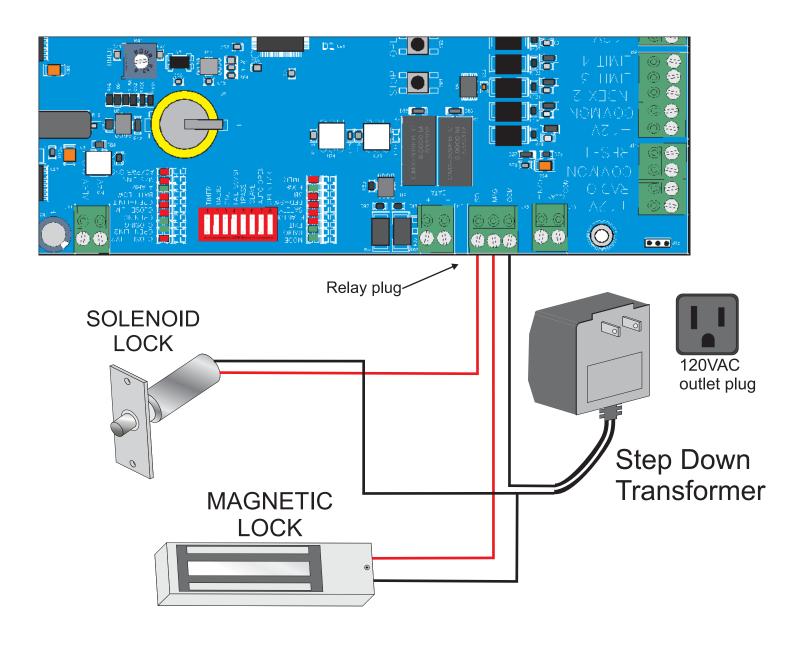


## **MAGNETIC/SOLENOID LOCK CONNECTION**

Magnetic lock installation requires a step down transformer with appropriate voltage for the specific lock accessory. Operator will provide a 120VAC outlet for the step down transformer.

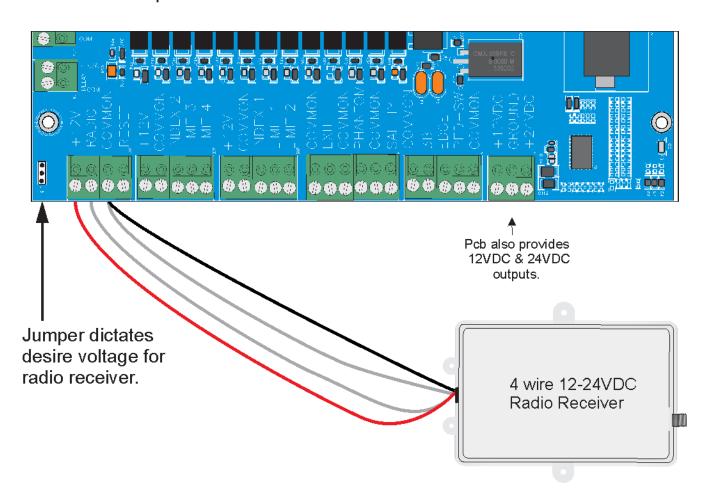
**Connections:** Plug the lock device transformer to the 120VAC outlet plug. **For Magnetic lock:** Connect one wire from transformer directly to one wire of the magnetic lock, the other wire from transformer will be connected to the relay plug COM input and the MAG relay output connects to the other wire of the magnetic lock. See illustration below.

**For Solenoid lock:** Connect one wire from transformer directly to one wire of the solenoid lock, connect the other wire from transformer to the relay plug COM input and the SOL relay output

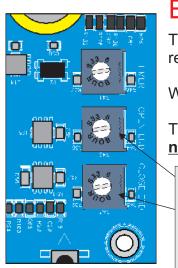


## RADIO RECEIVER CONNECTIONS

**4 wire receiver:** connect the two relay wires to 1 & 2 terminals. Black **negative** wire to terminal 1 and Red **positive** wire to terminal 3 on receiver strip outside control box as shown below.



#### **OPEN AND CLOSE OBSTRUCTION SENSITIVITY ADJUSTMENT (ERD)**

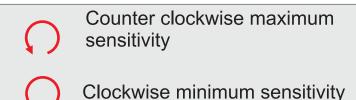


### ERD'S must be adjusted by qualified technician.

The gate operator ERDs must be adjusted so that the gate provides regular, reliable and safe operation.

When gate stops and reverses by itself, the ERD is too sensitive.

The gate must stop and reverse when it hits an obstruction or the ERD is **not sensitive enough.** 



ERD must be checked every six months.

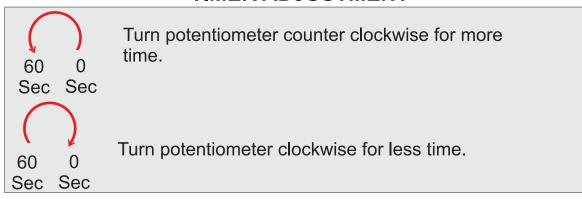
## TIMER ADJUSTMENT

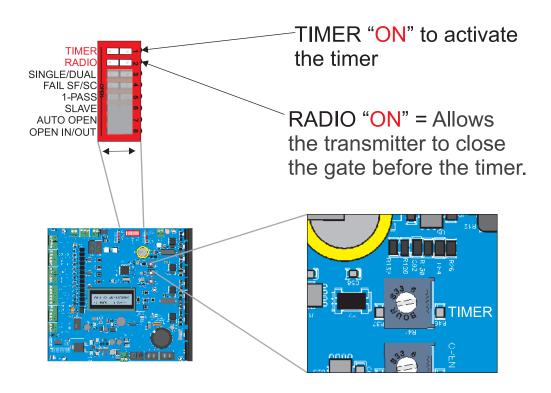
TIMER ON: Timer to close, can be set from 1 to 60 seconds.

TIMER OFF: Gate operation is push button to open, push button to close.

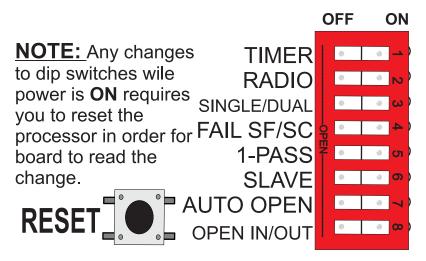
TO OVERRIDE THE TIMER: Turn the RADIO switch to the "ON" position. This will allow the radio receiver to close the gate before the timer.

#### **TIMER ADJUSTMENT**





## **DIP SWITCH FUNCTIONS**



#### **TIMER**

**TIMER** switch "**ON**" activates the TIMER. See page 21 for details

#### **RADIO**

**RADIO** switch "**ON**" allows the radio receiver to override the timer. See page 21 for details.

#### SINGLE/DUAL

This switch is used to select single or dual motor operation. **OFF** will only run motor 1 and **ON** will run motor 1 and motor 2.

#### FAIL SF/SC

This is to set the operator as fail-safe or fail secure. **ON** for **Fail-safe**: on power failure, board will monitor battery voltage to make sure gate opens before battery drains out completely. **OFF** for **Fail-secure**: on power failure gate will run until battery is low and stay close.

#### 1-PASS

This is a true one pass, anti-tailgating feature. This feature may only be used with safety loops. With this switch in the "**ON**" position, the gate will open until one car passes the safety loops then it will stop and close. If a second car pulls on the loop the gate will stop the car must then back off the loop before the gate will close.

#### **SLAVE**

This feature is used on master/slave setups. Set slave switch "**ON**" on slave machine, all other switches "**OFF**". Set slave switch to the "OFF" position on master machine. Set other function switches on master machine as desired. See page **17** for more details on master/slave connections and settings.

#### **AUTO OPEN**

This feature is to automatic open the gate on power interruption. It is a very particular feature used in areas where the fire department requires the gate to open automatically after a power outage. Set this dip switch "ON" when this feature is desire.

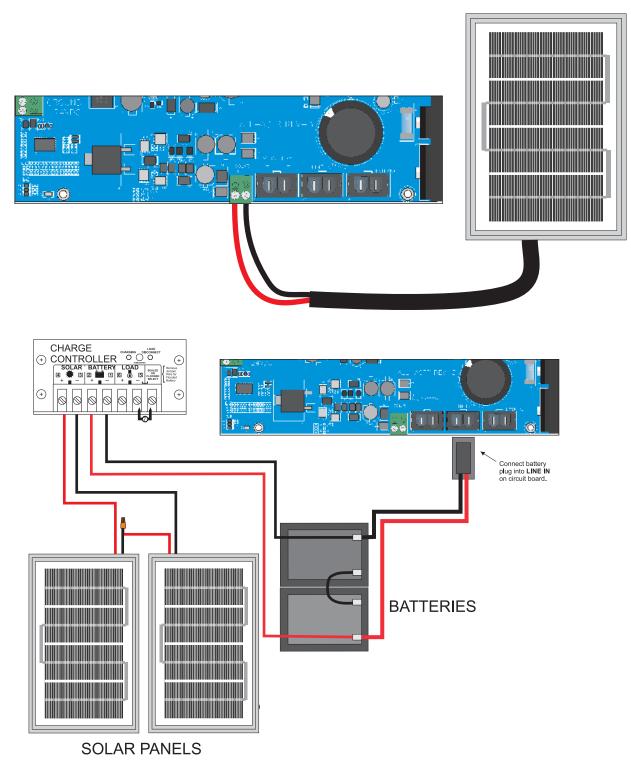
#### **OPEN IN/OUT**

This feature is to set the opening direction. OFF is to open in and ON to open out.

## **SOLAR PANEL CONNECTION**

The solar panel input will take a 12 or 24VDC panel or two 12VDC panels wired in series to make 24VDC. The on-board charger is limited to 80 watts. For applications that require more than 80 watts an external charger is required. See diagrams below for the different connection options.

NOTE: For information on solar panel calculation call ALL-O-MATIC or your local distributor for Assistance.



### **LED DIAGNOSTICS**

**AC/PWR ON:** Will be lit when power is present at LINE-IN power input.

**ALARM:** Two states;

1st state: LED will blink (horn will beep also) every 30 seconds when battery is low, bad or

disconnected.

2nd state: LED will turn on for 5 minutes when operator goes into shut down mode do to the

gate hitting an obstruction (E.R.D.). Also, the horn will go off for 5 minutes.

LOW BATTERY: LED will be on solid when battery is low.

**MODE:** Two states:

1st state: LED will blink slow (about every 2 seconds) when an overload occurs (over current). 2nd state: LED will blink fast (about every  $\frac{1}{2}$  second) when gate is jammed or motor sensors are not responding or disconnected.

not responding or disconnected.

**OPEN LIM:** LED will be on while the open limit switch on MOTOR 1 is active.

**OPEN LIM2:** LED will be on while the open limit switch on MOTOR 2 is active.

**CLOSE LIM:** LED will be on while the close limit switch on MOTOR 1 is active.

**CLOSE LIM2:** LED will be on while the close limit switch on MOTOR 2 is active.

**OPENING**: LED will be on while the board is sending power to either MOTOR 1 and/or MOTOR 2 for opening direction.

**CLOSING**: LED will be on while the board is sending power to either MOTOR 1 and/or MOTOR 2 for closing direction.

**RADIO**: LED will be on while radio input is activated (closed circuit to common).

**EXIT**: LED will be on while exit input or OPEN push button are activated (closed circuit to common).

**PHANTOM**: LED will be on while phantom input is activated (closed circuit to common).

**SAFETY**: LED will be on while safety input is activated (circuit is open from common).

**PED-SW**: LED will be on while ped-sw input is activated (circuit is open from common).

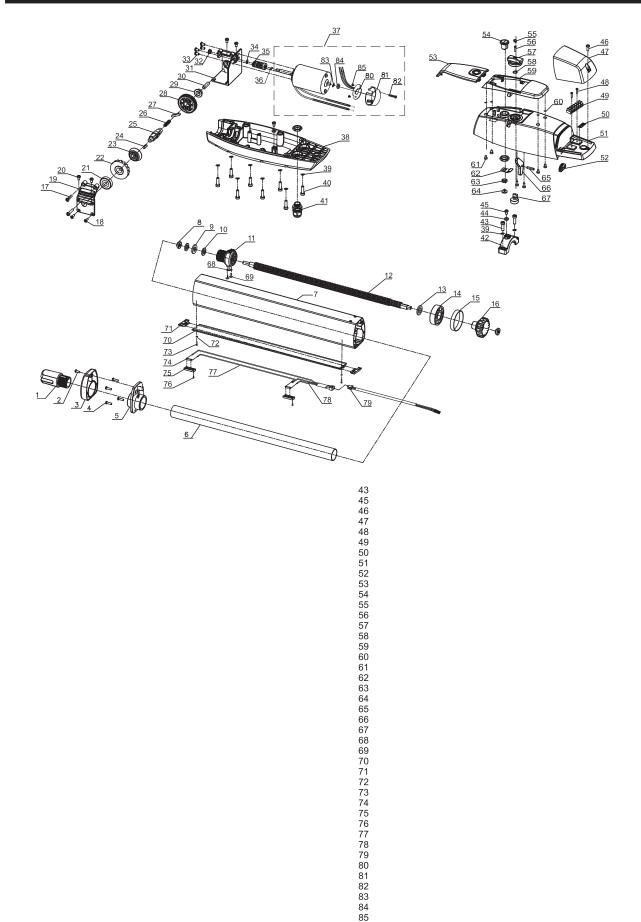
**3BT**: LED will be on while 3bt input or CLOSE push button are activated (closed circuit to common).

**EDGE**:LED will be on while edge input is activated (closed circuit to common).

**TIMER LED**: LED will blink when timer is counting down (on the open position only).

**M/S LINK**: This is only for Master/Slave set up. Since this board is capable of running two motors is not been used.

## **OPERATOR PARTS DIAGRAM**



 $\begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \\ 9 \\ 10 \\ 11 \\ 21 \\ 13 \\ 14 \\ 15 \\ 6 \\ 17 \\ 18 \\ 19 \\ 22 \\ 22 \\ 24 \\ 22 \\ 24 \\ 22 \\ 24$